17527

2	171	8												
3	Ho	ours		10	0 Marks	Seat	No.							
	Instri	uctions	s –	(1)	All Questions a	are Comp	oulsory	ν.						
				(2)	Answer each n	ext main	Ques	tion o	on a	a ne	ew	pag	e.	
				(3)	Illustrate your a necessary.	answers v	with r	neat s	ketc	hes	wł	here	ever	
				(4)	Figures to the	right indi	icate	full n	nark	s.				
				(5)	Assume suitable	e data, if	nece	ssary.						
				(6)	Use of Non-pro Calculator is pe	ogrammat ermissible	ole El e.	ectror	nic 1	Poc	ket			
				(7)	Mobile Phone, Communication Examination Ha	Pager an devices all.	d any are n	othe ot per	r E rmis	lect ssibl	roni le i	ic n		
]	Ma	rks
1.	a)	Atte	mpt	any	THREE of the	e followi	ng:							12
		i)	Stat pro	te the	e need and impose s. (Two points	ortance o each)	f non	-tradit	tion	al r	nac	hini	ng	
		ii)	Exp nea	olain t ske	the working of tch.	wire-cut	EDM	l proc	ess	wi	th			
		iii)	Stat	te the	e meaning of G	03, G40,	M03	, M06	5.					
		iv)	Wri	ite do	own the classific	cation of	borin	g ma	chin	le.				
	b)	Atte	mpt	any	<u>ONE</u> of the fo	ollowing:								6
		i)	Des two	scribe adv	the working of antages of LBM	f LBM v 1.	vith n	eat sl	cetc	h. S	State	e ar	ny	
		ii)	Stat the	te the safe	e importance of ty procedures to	dry run be follo	in Cl wed	NC m while	ach usi	ine; ng	Er CN	nlist C	-	

P.T.O.

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machines.

16

2. Attempt any FOUR of the following:

- a) State any four essential requirements of dielectric fluid used in EDM.
- b) Explain closed loop control system with neat sketch.
- c) Explain the construction of planomiller with neat sketch.
- d) Write down the detailed classification of milling machine.
- e) State the objectives and need of maintenance (2 points each)
- f) Compare traditional and non-traditional machining processes. (Four points each)

3. Attempt any TWO of the following:

 a) Write a part program for job as shown in Fig. No. 1. Take only finish cut. Use, Spindle speed = 1500 rpm and feed rate = 0.1 mm/rev. Assume suitable data if necessary.



- b) Explain the working of PAM with neat labelled sketch. State its any two applications.
 - c) What is the function of dividing head? Sketch and explain internal mechanism of universal dividing head.

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16

Marks

4. Attempt any THREE of the following: 12 a) Differentiate between up-milling and down milling. i) (Four points each) Explain gear hobbing process with neat sketch. ii) iii) Explain honing process with neat sketch. What is repair complexity? State its use in maintenance iv) of machine tools. (Any two) 6 Attempt any ONE of the following: b) Explain the stepwise process of manufacturing hexagonal i) shape on milling machine. Explain, how grinding wheels are specified. ii) 5. Attempt any FOUR of the following: 16 a) Explain repair cycle analysis. State its uses in maintenance of machine. (Any two) b) What is burnishing? State its advantages. c) What is meant by grinding wheel dressing? Why wheel dressing is necessary? d) Explain with neat sketch gear grinding using form wheel. Differentiate between capstan and turret lathe. (Four points each) e) f) Sketch any two types of boring tools. 6. Attempt any FOUR of the following: 16 a) Define feed/tooth and feed/revolution in milling operations. b) Draw sketch showing different elements of broach and state the function of any two elements. c) Compare preventive maintenance with break-down maintenance. (Four points)

- d) Enlist the advantages and limitations of broaching. (Two points each)
- e) What is cutter tool compensation? Why it is required in CNC machine part programming.
- State any four criteria of selecting the grinding wheel for, any f) specific application.



Subject Name: Advanced Manufacturing Process Model Answer

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills.
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q. No	Bit No.	Description/ Answer	Marks
Q1	a.	Attempt any Three of the Following	12
	i)	 i) State the need and importance of non – traditional machining process. (Two point each) Need of non – traditional machining process. (1) The need to shape new metal alloys and non-metals that are difficult to machine by conventional processes; (2) The requirement of unusual and complex workpart geometries. (3) The need to avoid surface damage which is often associated with conventional machining Importance of Nontraditional Machining process. 1. Material removal may occur with chip formation or even no chip formation may take place. 2. In NTM, there may not be a physical tool present. 3. In NTM, the tool need not be harder than the work piece material. 4. Mostly NTM processes do not necessarily use mechanical energy to provide material removal. 5. They use different energy domains to provide machining. 	Any 2 2 marks Any 2 2 marks
	ii	ii) Explain the working of wire-cut EDM process with neat sketch.	Fig 02 Marks



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			Wire feed	Marks
			M.	
			Moving wire Nozzles for electrode Dielectric fluid	
		12	S A	
			Workpiece	
			JAK .	
			\times (0)	
			motions Enlarged view of	
		er e	vechansim	
		The basic mechanism of moto	I removed in WEDM is identical to that in dis sinking type EDM	
		Instead of moving electrode	the electrode in this process is a moving wire of CU or brass.	
		vertically oriented wire is fed	into the work piece continuously travelling from a supply spool to	
		take a spool, so that it is contin	uously renewed, since it will get worn out during the process.	
		(III) State the meaning of G03	, G40, M03, M06	
		Codes in part programming	Weating	
		G03	Circular interpolation Anticlockwise	Each 1
	iii	G40	Cutter diameter compensation Cancel	Lach 1 Marks
				iviai K5
		M03	Spindle start Clockwise	
		M06	Tool Change	
		1 Horizontal Boring Machine	ion of boring machine.	
		- Table type		
		- Floor Type		
	:. .	- Planer Type		4 Montra
	IV	2. Vertical Boring Machine		4 WIAFKS
		- Stander vertical Bori	ng Machine	
		-Vertical Turret lathe		
		5. Jig bornig Machine		
		4. Precision boring machine.		
1	b.	Attempt any <u>ONE</u> of the follo	owing	6
L	1	1		I



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	The name indicates that the closed loop control system has a loop that is closed as shown in fig. A	03 marks				
	Feedback signal	03 marks				
b)	Linear motion of work table Workpiece Table slide Input MCU Stepper MCU Stepper MCU Lead screw					
	Fight electric strengthb) Explain Closed loop control system with neat sketch.	01 marks				
	- Freedom from acid & alkaline products					
	- Controlled level of toxicity					
a)	- High flash point	04 marks				
	- Low viscosity					
	a) State any four essential requirements of dielectric fluid used in EDM					
	machine such as curtain guards, contact mats, guard fencing, soundproof casing, and emergency stop button operation to ensure a safe CNC machining operation.Attempt any FOUR of the following:	16				
	In any workplace, safety comes first. Operators must understand all the safety features on the					
	can conduct electrical charges as well as getting caught in machinery. Wearing loose clothing is also prohibited since the operator risks getting pulled into the machinery, and this can be quite fatal.					
	4. Operators Must Dress Accordingly					
	Before beginning the actual CNC machining process, the operator must conduct a trial run to ensure that all moving parts are set and configured correctly. Most machines have a lock feature that allows users to scan the program for mistakes. During this process, the spindle will run, the control will execute the program, and the turret will index. However, only the axes (X, Y and Z) will stay still.					
	3. Conducting a Dry Run Is Important					
	Before a machining or tooling process is initiated, the machinist must inspect the machine to remove any obstacles that may fly off and hit someone. The user must check the path of the router to ensure that there are no screws that can stay embedded in the project. The floor should be clear of sawdust and scraps to prevent any possible accidents.					
		Before a machining or tooling process is initiated, the machinist must inspect the machine to remove any obstacles that may fly off and hit someone. The user must check the path of the router to ensure that there are no screws that can stay embedded in the project. The floor should be clear of sawdust and scraps to prevent any possible accidents. 3. Conducting a Dry Run Is Important Before beginning the actual CNC machining process, the operator must conduct a trial run to ensure that all moving parts are set and configured correctly. Most machines have a lock feature that allows users to scan the program for mistakes. During this process, the spindle will run, the control will execute the program, and the turret will index. However, only the axes (X, Y and Z) will stay still. 4. Operators Must Dress Accordingly Users should never wear gloves while operating the machinery. Wearing loose clothing is also prohibited since the operator risks getting pulled into the machinery, and this can be quite fatal.In any workplace, safety comes first. Operators must understand all the safety features on the machine such as curtain guards, contact mats, guard fencing, soundproof casing, and emergency stop button operation to ensure a safe CNC machining operation. Attempt any FOUR of the following:				



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Hand milling machine I. II. Plain milling machine III. Universal milling machine IV. Vertical milling machine b. Fixed bed type milling machine I. Simplex milling machine II. Duplex milling machine III. Triplex milling machine c. Planer milling machine d. Special type of milling machine I. Rotary table milling machine II. Planetary milling machine III. Profiling milling machine Duplicating milling machine IV. V. Pantograph milling machine VI. Tracer contour miling machine e) State the objectives and need of maintenance (2 point each) objectives To minimize the number of breakdown. To keep plant in good working condition at the lowest possible cost. 02 marks To minimize the hindrance and interruption of work. Any 2 To carry out the work of all the machines smoothly. e) need of maintenance Maintenance should be planned at regular intervals to prevent uncalled breakdown. If proper attention is not given to the machine tool then it will fail. 02 The maintenance of machine tool is needed to keep them in working condition at all the marks times. Any 2 The maintenance of machine tool is important to minimize the hindrance and interruption of work. f) Compare traditional and non-traditional machining processes. (Four point each) **Traditional Machining Processes Non- Traditional Machining Processes** 1. Generally macroscopic chip formation by 1. Material removal may occur with chip shear deformation. formation or even no chip formation may [any 4 take place. 2. There may not be a physical points 4 f) 2. There may be a physical tool present. tool present. marks] 3. Cutting tool not harder than work piece 3. Cutting tool is harder than work piece 4. Mostly NTM processes do not necessarily use mechanical energy to 4. Material removal takes place due to provide material removal. They use application of cutting forces – energy different energy domains to provide domain can be classified as mechanical machining. For example, in USM, AJM,



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						WJM mechanical energy is used to	
		5. Con	ventional mach	ining involves t	the	machine material, whereas in ECM	
		direct	contact of tool	and work –piec	e	electrochemical dissolution constitutes	
						material removal.	
		6. Low	ver accuracy and	d surface finish.		5. Whereas unconventional machining does	
			, and the second s			not require the direct contact of tool and	
		7. Suit	able for every t	vpe of material		work piece.	
		econo	mically	51		6. Higher accuracy and surface finish.	
			2			7. Not Suitable for every type of material	
		8. Too	l life is less due	to high surface	è	economically	
		contac	t and wear.	C		8. Tool life is more	
		9. Hig	ner waste of ma	terial due to high	gh	9. Lower waste of material due to low or no	
		wear.			-	wear.	
		10. No	isy operation m	nostly cause sou	ind	10. Quieter operation mostly no sound	
		pollut	ions			pollutions are produced.	
		11. Lo	wer capital cos	st		11. Higher capital cost	
		12. Ea	sy set-up of equ	uipment.		12. Complex set-up equipment.	
		13. Sk	illed or un-skill	ed operator may	у	13. Skilled operator required.	
		requir	ed			14. Generally they are fully automated	
		14. Ge	nerally they are	e manual to oper	rate.	process.	
		15. Th	ey cannot be us	sed to produce		15. Can be used to produce prototype parts	
		protot	ype parts very e	efficiently and		very efficiently and economically.	
		econo	mically.				
3		Attemp	t any Two of t	he following:			16
		Write	nort program	for a job show	en in Fie	No 1. Take only finish out Use spindle speed -	
	a.	Write a	part program	1 for a job show	vn in Fig v Assur	g No.1. Take only finish cut. Use, spindle speed =	08
	a.	Write a 1500 rp	part program m and feed rat	t for a job show te = 0.1 mm/re	vn in Fig v. Assun	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary.	08
	a.	Write a 1500 rp	part program m and feed ra	tor a job show te = 0.1 mm/re	vn in Fig v. Assun (02 M	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Jarks for Detailed Figure and Coordinates & 06	08
	a.	Write a 1500 rp Point	part program m and feed rat	te = 0.1 mm/rev	vn in Fig v. Assun (02 M Mark,	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program)	08
	a.	Write a 1500 rp Point	part program m and feed ra X- Coordinate	te = 0.1 mm/re Z- Coordinate	vn in Fig v. Assun (02 M Mark.	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program)	08 02 Marks
	a.	Write a 1500 rp Point Point	A part program m and feed rat X- Coordinate 0.0	te = 0.1 mm/rev Z- Coordinate 5.0	vn in Fig v. Assun (02 M Mark Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for
	а.	Write a 1500 rp Point Point	x- Coordinate	te = 0.1 mm/rev Z- Coordinate 5.0	vn in Fig v. Assun (02 M Mark, Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for
	a.	Write a 1500 rp Point P0 P1	X- Coordinate 0.0	a for a job show te = 0.1 mm/rev Z- Coordinate 5.0 0.0	vn in Fig v. Assun (02 M Mark: Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed
	а.	Write a 1500 rp Point Point P ₀ P ₁	X- Coordinate 0.0	a for a job show te = 0.1 mm/rev Z- Coordinate 5.0 0.0	vn in Fig v. Assun (02 M Mark, Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed
	a.	Write a 1500 rp Point P0 P1 P2	part programm and feed rateX- Coordinate0.00.020.0	Z- Coordinate 5.0 0.0 0.0 0.0	vn in Fig v. Assun (02 M Mark: Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure,
	a. An s	Write a 1500 rp Point P0 P1 P2 P3	part program m and feed rateX- Coordinate0.00.020.040.0	z z Z- Coordinate 5.0 0.0 0.0 -10.0	vn in Fig v. Assun (02 M Mark. Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin
	a. An s	Write a 1500 rp Point P0 P1 P2 P3	part program m and feed rateX- Coordinate0.00.020.040.0	Z- Coordinate 5.0 0.0 -10.0	vn in Fig v. Assun (02 M Mark: Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4	part program m and feed rateX- Coordinate0.00.020.040.040.0	z z Z- Coordinate 5.0 0.0 0.0 -10.0 -30.0 -30.0	vn in Fig v. Assun (02 M Mark. Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4	part program m and feed rateX- Coordinate0.00.020.040.040.0	Z- Coordinate 5.0 0.0 -10.0 -30.0	vn in Fig v. Assun (02 M Mark, Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4 P5	part program m and feed rate X- Coordinate 0.0 20.0 40.0 40.0 60.0	a for a job show te = 0.1 mm/rev Z- Coordinate 5.0 0.0 -10.0 -30.0 -80.0	vn in Fig v. Assum (<i>02 M</i> <i>Mark.</i> Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. <i>Tarks for Detailed Figure and Coordinates & 06</i> <i>s for Correct Program</i>) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4 P5 P6	part program m and feed rate X- Coordinate 0.0 20.0 40.0 60.0 60.0	a for a job show te = 0.1 mm/rev Z- Coordinate 5.0 0.0 -10.0 -30.0 -80.0 -120.0	vn in Fig v. Assun (02 M Mark, Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. Marks for Detailed Figure and Coordinates & 06 s for Correct Program) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates &
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4 P5 P6	part program m and feed rate X- Coordinate 0.0 20.0 40.0 60.0 60.0	a for a job show te = 0.1 mm/res Z- Coordinate 5.0 0.0 -10.0 -30.0 -80.0 -120.0	vn in Fig v. Assun (<i>02 M</i> <i>Mark</i> . Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. <i>Tarks for Detailed Figure and Coordinates & 06</i> <i>s for Correct Program</i>) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates &
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4 P5 P6 P7	part program m and feed rate X- Coordinate 0.0 20.0 40.0 60.0 60.0 70.0	a for a job show te = 0.1 mm/rev Z- Coordinate 5.0 0.0 -10.0 -30.0 -80.0 -120.0 -120.0	vn in Fig v. Assun (02 M Mark, Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. <i>Tarks for Detailed Figure and Coordinates & 06</i> <i>s for Correct Program</i>) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates &
	a. An s	Write a 1500 rp Point P0 P1 P2 P3 P4 P5 P6 P7	part program m and feed rate X- Coordinate 0.0 20.0 40.0 60.0 60.0 70.0	a for a job show te = 0.1 mm/res Z- Coordinate 5.0 0.0 -10.0 -30.0 -80.0 -120.0 -120.0	vn in Fig v. Assum (<i>02 M</i> <i>Mark.</i> Figur	g No.1. Take only finish cut. Use, spindle speed = ne suitable data if necessary. <i>Tarks for Detailed Figure and Coordinates & 06</i> <i>s for Correct Program</i>) re of work piece with its Coordinates	08 02 Marks for Detailed Figure, Coordin ates &



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				06
		01234;	Program no.	Marks
	N001	G28 U0.0 W0.0;	Return to reference position	for
	N002	G21 G90 G99 G97;	Input in mm, Absolute Programming,	Correct
			G99 for Feed in mm/rev&G97 for speed in rpm	Program
	N003	M06 T0101 M08;	Tool change tool no. tool offset no. coolant ON	
	N004	M03 S1500;	Spindle Start clockwise with 1500 rpm	
	N005	G00 X0.0 Z5.0;	Move the tool rapidly to point P ₀	
	N006	G01 X0.0 Z0.0 F0.1;	Move the tool with Feed rate of 0.1mm/rev to point P_1 (Touch point)	
	N007	G01 X20.0 Z0.0;	Facing Operation up to point P ₂	
	N008	G03 X40.0 Z-10.0 R10;	After facing circular Interpolation CCW with Radii =10 mm up to point P_3	
	N009	G01 X40.0 Z - 30.0;	After radius of 10 mm plain turning	
			up to point P ₄	
	N010	G01 X60.0 Z - 80.0;	After that taper turning up to point P ₅	
	N011	G01 X60.0 Z - 120.0;	After taper turning plain turning up to point P ₆	
	N012	G01 X70.0 Z – 120.0;	Lastly tool is taken away from work piece	
			up to point P7	
	N013	M09 M05;	Coolant STOP, Spindle STOP	
	N014	G28 U0.0 W0.0;	Return to reference position	
	N015	M30;	End of Program	
b.	Explain	the working of PAM with neat l	abelled sketch. State its any two applications.	08
An	(03 Mark Plasma A	ts for Working, 03 Marks For Sk Arc Machining:	tetch & 01 Mark For Each Application)	03
S	high about shown in	at 11000 to 30000 degree centigration the figure. In this process, plas	ade ionized gas on the work piece. The principle PAM is sma torch is used in which a volume of a gas such as	Marks
I	1	<u> </u>	rueextams.com	



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H2,N2,O2 is passed through a small chamber in which high frequency spark is maintained between cathode and anode. The plasma jet melts the work piece material. The depth of hat zon depends on the work material ,its thickness and cutting speed.	d for e Working
Cas/Gas michure	, 03 Marks
$(H_2, N_2, O_2) \longrightarrow $	For
Chamber	Sketch
Arc	&
High temperature Anodic	01
nozzie	Mark For
Workpiece	Each
Plasma Arc Machining (PAM). Applications of PAM: (1) Cutting Alloy Steels, Stainless Steels, Aluminium and its alloys	Applicati on
 (2) Used for turning and milling of difficult to machine materials (3) Used for removing of gates and risers from a casting. (4) Used in underwater operations like, in shipyards, chemical industries, nuclear power platetc. 	t,
 (5) Used for cutting of hot extrusions What is the function of dividing head? Sketch and explain internal mechanism of universal 	
c dividing head.	08
An s(02 Marks for Function & 04 Marks for Sketch & 02 Marks For Explanation)Function of Dividing Head: Function of dividing head is to divide the periphery of a workpiece into any number of equal part For example: (1) If we want to make a hexagonal bolt. Head of the bolt is given hexagonal shape. We divide xing to divide circular workpiece into six equal parts and then all the six parts are milled to a identical flat surface. (2) If we want to cut "n" number of teeth in a gear blank. The circumference of gear blank divided into "n" number of equal parts and teeth are made by milling operation one by one. Universal Dividing Head:	s. o n s



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ii An s	Explain (02 Ma	n gear hobbing process with neat sketc	h. ation)	04 02 Marks For Sketch & 02
	9	Chips get deposited on un- machined surface of work piece.	Chips get deposited on machined surface of work piece.	
	8	The cutting force is downward at the beginning of cut and reaches to upward at the end of cut.	The cutting force is upward at the beginning of cut and reaches to downward at the end of cut.	
	7	The cutter does not start cutting metal as soon as it come in contact with work piece	The cutter start cutting metal as soon as it come in contact with work piece	
	6	Wavy surface finish is obtained	Better surface finish is obtained	
	4	Cutting force tends to lift the workpiece from the fixture.	Cutting force tends to seat the work piece from the fixture.	
	3	The chip thickness progresses gradually from start of cut to end of cut	The chip thickness is maximum at the beginning of cut and minimum at the end of cut	
	2	In Conventional Milling cutter rotates in direction opposite to that in which the work is fed.	In climb Milling cutter rotates in direction same to that in which the work is fed.	
		Cutting motion Depth of cut Conventional, or up milling	Cutting motion	
	1			



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 	-Hob-	Marks
	Axis of rotation Gear blank Gear blank	For Explanat ion
	In this process of gear generating a tool is used known as hob. Hob teeth are shaped to match the tooth space and are interrupted with grooves to provide cutting surfaces. It rotates about an axis normal to that of the gear blank, cutting into the rotating blank to generate the teeth as shown in figure.	
	It is the most accurate of the roughing processes since no repositioning of tool or blank is required and each tooth is cut by multiple hob-teeth, averaging out any tool errors. Excellent surface finish is achieved by this method and it is widely used for production of gears.	
iii	Explain honing process with neat sketch.	04
	 (02 Marks For Sketch & 02 Marks For Explanation) Honing:- It is a superfinishing operation used for previously machined surfaces. It is used for finishing internal cylindrical surfaces, drilled or bored holes. The tool is called as Hone which is made out of bonded abrasive stone made in the form of stick. The tool moves back & fourth while rotating about its axis. Honing operation can be done by two methods. a) Hand honing; for small lot of workpieces b) Machine honing: for large scale Production Special Honing machines are used 	02 Marks For Sketch
An s	Rotary Motion Back & Forth Motion	& 02 Marks
	Horing Tool Workpiece	For Explanat ion
iv	What is repair complexity? State its use in maintenance of machine tools (Any two)	04
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		(02 Marks For Definition & 01 Mark For Its Each Use)	02
		Repair Complexity:	Marks
		Repair Complexity is defined as the extent of complexity of machine tool considered for the	For
		maintenance work which is represented by a comparative index number. This number is called as repair complexity number . Use of Repair Complexity in Maintenance of Machine Tool:	Definitio n
		(1) If the repair complexity number is high, then repair cycle of the machine is longer because it consist high number of maintenance activities.	&
	An s	(2) Repair complexity number is useful to decide the number of staff required for maintenance.	01
		(3) To decide inventory of spares required for maintenance.(4) To decide inventory of spares required for maintenance.	Mark
		(4) To decide the repair cycle of the particular machine.(5) To find out the number of critical maintenance points of the machine.	For
		(6) To forecast the maintenance cost of the machine or plant.(7) Also maximum lastice devides the time interval of maximum last	Its
		(7) Also repair complexity decides the time interval of repair cycle.(8) On the basis of repair complexity number maintenance schedule is prepared for the	Each
		machine or plant.(9) For higher number long schedule is prepared while for small complexity number short	Use
		schedule is needed.	
4	b	Attempt any ONE of the following:	06
	i	Explain the stepwise process of manufacturing hexagonal shape on milling machine.	06
		(03 Marks for Explanation & 03 Marks For Figure)	03
		Straddle Milling Operation For Hexagonal Shape:	Marks
		[1] This is similar to the side milling operation. Two side milling cutters are mounted on the same	for
		[2] Distance between them is so adjusted with the help of spacing collars such that both sides of the work piece can be milled simultaneously.	Explanat ion
	An	[3] Hexagonal Shape can be produced by this operation by rotating the work-piece only two times as this operation produces two parallel faces of hexagonal shape simultaneously	&
	s		03
		- JS - Martin	Marks
			For
		and the second sec	Figure



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	ii	Explain, how grinding wheels are specified	06		
		(02 Marks for Size Specification & 04 Marks For Remaining Specification)(Note: Figure is not	02		
		Grinding Wheel Specification:			
		Example:			
		D	for		
			Size		
		Grinding	Specifica		
		face	tion &		
			04		
		450 X 75X 101 6 ROS 200 X 2551 A 36 L 5 40	Marke		
	An	D = 450 = Outer diameter of grinding wheel	1 1121 NS		
	S	T = 75 = width of grinding wheel	For		
		H = 101.6 = Bore of grinding wheel	Remaini		
		ROS = Recess One Side	ng		
		P = 200 = Diameter of Recess	Specifica		
		F = 25 = Depth of Recess 51 - Menufacturers Sumbal	tion		
		SI = Manufacturers Symbol. A = Type Of Abrasive (Aluminium Oxide)	Notes		
		$\mathbf{A} = 1$ ype of Abrasive (Aluminium Oxide) $36 = \mathbf{Grain size}$ (Medium)	(Note: Figure is		
		L = grade (Medium)	rigure is		
		5 = structure (Dense)	compulso		
		$\mathbf{V} = $ bond (Vitrified)	rv)		
		40 = manufacture symbol (<i>Optional</i>)			
5		Attempt Any Four of the following			
	a	Explain repair cycle analysis. State its uses in maintenance of machine			
		Repair Cycle Analysis			
		The repetitive performance of maintenance activities between two overhauling (inspection) is			
		called as repair cycle analysis.			
		For maintenance planning repair cycle analysis is important	2 Marks		
		i of maintenance praining repair eyere analysis is important.	foe		
	An		Explanat		
	S	Inspection	ion and		
		Repair -01	2 Marks		
		Majorrepair	for Use		
		Repair -02			
		WWW.treexams.com	<u> </u>		



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T			
		Repair cycle analysis involves:	
		[1] Primary Inspection:-	
		Proper examination of the machine tool is carried to identify the problem. In this stage root cause of the problem can be found out.	
		[2] Small Repair-01:-	
		In this stage as per the problem complexity cleaning or lubrication, type of small repair is performed.	
		[3] Small Repair-02:	
		After repair one if the problem still exists another small repairs like alignment, proper assembly, nut and bolt tightening is performed.	
		[4] Inspection:-	
		After small repair the machine tool is inspected for its performance.	
		[5]Major repair:-	
		If the small problem exists after small repair the major repair takes place like replacement of component or machining is required.	
		[6] Inspection:	
		After major repair the inspection carried out for effective and efficient performance of that machine tool.	
		Use of Repair Cycle Analysis	
		• It gives idea about staff required.	
		• Number of small/minor repairs.	
		• Number of major repairs.	
		Number of spare parts (quantity required for maintenance)	
	b	What is Burnishing State its advantages	
	An	Burnishing Burnishing is super finishing process of obtaining a very fine surface finish having grainless appearance on metal objects. This process is used on various flat,cylindrical or conical surfaces. It removes scratches and tool marks on the surface.	2 Marks for Explanat ion and
	S		1 Mark each for
		Advantages of Burnisning	any 2
		1. There is no cutting action in this process. Only rubbing and peening action takes place.	correct Advanta



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s	Gear Grinding is a very accurate method and is, though relatively expensive, more widely used for finishing teeth of different type and size of gears of hard material or hardened surfaces. The properly formed and dressed wheel finishes the gear teeth flanks by fine machining or abrading action of the fine abrasives.				for Explanat ion
			wheel		and 2 Marks for sketch
	The grinding wheel is dressed to the form that is exactly required on the gear. Need of indexing makes the process slow and less accurate. The wheel or dressing has to be changed with change in module, pressure angle and even number of teeth. Form grinding may be used for finishing straight or single helical spur gears, straight toothed bevel gears as well as worm and worm wheels.				
e	Differentiate between capstan and turret lathe				
	Sr. No.	Capstan Lathes	Turret Lathes		
	1	The turret of capstan lathe is mounted on slides on the saddle	The turret of the turret lathe is directly mounted on bed		1 Maula
An	2	Less rigidity provided to the tool	More rigidity provided to the tool		each for
All S	3	Suitable for light weight bar works	Suitable for Larger and heavier loads		any 4 correct
	4	Handy for small components	Larger works can be machined easily		points
	5	High production rate as fast cut is possible	High production rate cannot be achieve easily as larger and heavier parts do not permit fast cut		
f	Sketch ar	ny two types of boring tools			



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	An	[a] Light Boring Tool	[b] Forged Bo	pring tool	[c] Boring Bar	2 Marks each for any 2
	S	[d] Double ended Boring too	ol [e] Multiple Edges Bo	pring Tool [f]	Counter Boring Tool	correct drawing
6		Attempt any Four of the	following			
0		Attempt any Four of the	lonowing			
	Α	Define feed / tooth and f	eed / revolution in n	nilling operations		
	An s	 a) Feed per tooth (Sz):- The feed per tooth is defined by the distance the work advances in the time between engagement by the two successive teeth. It is expressed in mm/tooth of the cutter. b) Feed per revolution (Srev):-The feed per cutter revolution is the distance the work advances. 				
		in the time when the cutte	er turns through one c	omplete revolution	1.	ns
	b	Draw sketch showing di	fferent elements of l	proach and state t	the function of any two element	s
	An	Slot Pull end	Chip breakers	n → I≺Semi-* finishing teeth	Rear pilot	2 Marks for Sketch and
		 Elements of Broaches:- Pull end:- this is det Front pilot:- this cet Roughing and semited Finishing teeth:- th Rear Pilot:- They set Land :- the top port 	signed to permit enga ntres the broach in th i finish teeth:- They r ey are for sizing the h upport the broach afte ion of the tooth is cal	gement of the broa e hole before teeth remove most of the role and must require the last teeth leaves led as land	ach with the broaching machine begins to cut e stock in the hole ired shape of the finishing hole the work piece	1 Mark each for any 2 correct points
	с	Compare preventive maintennace with breakdown maintenance				
	An s	SNo. Preventive	e Maintenance	Breakde	own Maintenance	1 Mark each for
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	1	Actions performed on a time- or	Breakdown maintenance is basically the		any 4
		machine-run-based schedule that	"run it till it breaks" maintenance mode. No	C	correct
		detect, preclude, or mitigate	actions or efforts are taken to maintain the	F	points
		degradation of a component.	equipment		
	2	Reduced equipment or process	Increased cost due to unplanned downtime		
		failure.	of equipment		
	3	Less labor cost because of planned	Increased labor cost, especially if overtime		
		maintenance.	is needed.		
	4	Estimated 12% to 18% cost savings	Cost is involved with repair or replacement		
		over breakdown maintenance	of equipment		
		program.			
	5	Increased component life cycle.	Possible secondary equipment or process		
			damage from equipment failure		
	6	Efficient use of staff resources	Inefficient use of staff resources		
d	Enlist tl	ne advantages and limitations of bros	aching		
u	Emist the advantages and minitations of broaching				
	Advantages				l Mark
					ach for
	[1] Advantages:-				any 2
	1)	Rate of production is very high		C	correct
	2) Semiskilled operator can perform the operation				avantag
	3) High accuracy				es
	4) High surface finishing				
An	5) Both roughing and finishing cuts are perform in one pass				
S	6)	The process can be used for internal ar	nd external surfaces		And
	Disauva	intages		1	l Mark
	1) High tool cost				ach for
	2) Very large work pieces cannot be machined				any 2
	3) The surfaces to be broach cannot have an obstruction				correct
	4) Large amount of stock (Material removal) cannot be removed				isadvan
	5) Work pieces must be rigidly supported				tages
e	What is cutter tool compensation? Why it is necessary in CNC machine part programming			ing	
	When n	nilling a contour, the tool radius cent	er is used as the reference point on the tool	while 2	Marks
	writing the program, but the part is actually cut by the point on the cutter periphery. This point is			oint is	for
An	at 'r' dis	tance from the tool center. This mean	ns that the programmer should shift the tool c	center E s	xplanat
S	away fr	om the part in order to perform the o	cutting by the tool cutting edge. The shift an	nount	ion
	depends upon the part geometry and tool radius. This technique is known as tool radius			adius	
	compens	sation or cutter radius compensation.			



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		and
	Necessity of Cutter Tool Compensation	
	[1] Cutter compensation allows programming the geometry and not the toolpath.[2] It also allows adjusting the size of the part, based on the tool radius used to cut part.[3] This is useful when cutter of the proper diameter is not found.	2 Marks for Necessity
f	State any four criteria of selecting the grinding wheel for any specific application	
	Selection criteria:-	
An s	 Material to be ground:- Grain size , grade, structure, bond Amount of stock to be removed:- This involves accuracy and surface finishing, coarse grain is used for fast cutting & fine grains are used for fine finish Area of contact:- Fine grain and closed grain spacing are useful where area of contact is small Type of grinding machine:- Heavy rigidly constructed machine used softer wheel. Wheel speed Work speed Condition of the machine Personal factor 	1 Mark each for any 4 correct points